

Post image to LINE with ESP32 [M5Stack-TimerCamera]

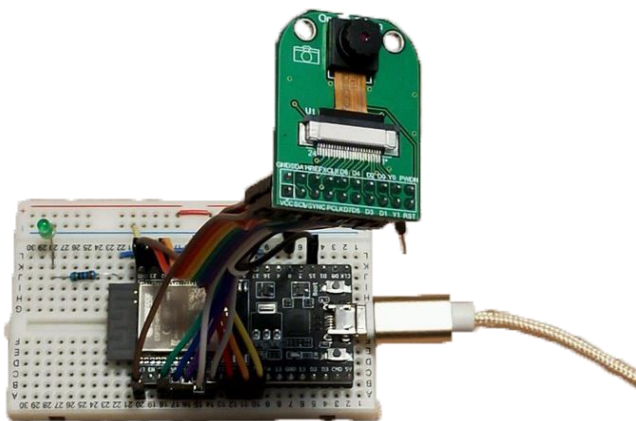

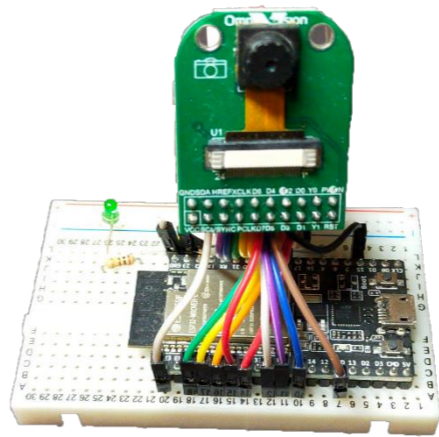

- HTTPS (TLS) client implementation
- Image posting using LINE-API

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4. LINE settings (token acquisition)
5. Arduino program
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1-1. Equipment selection (target around 4000 yen or less)






*Please note that the cost varies depending on the season.

		Same hardware configuration		Similar hardware configuration	
		①ESP32 (WROOM) and OV2640	②M5Stack UnitCam (OV2640)	③ESP32 (WROVER) and OV2640	④M5Stack TimerCamera (OV3660)
Figure					
Specification	Memory [SRAM]: 520kbyte, Resolution: 2M pixel			Memory [SRAM]: 8Mbyte	
	プログラム書込にはキットが必要*1			Resolution: 2M pixel	Resolution: 3M pixel
Usage	Image			Image, Video	
Cost	¥3930	M5Stack: UnitCam \$18.95 [marutsu: ¥2946] + ¥1100*1		¥4080	M5Stack: F)\$19.95, X)\$17.95 [SwitchScience: F)¥2860, X)¥2596]
Soft	Almost Usable (There are differences in Arduino motherboard settings and port usage)				
Youtube Post	Saving images to GoogleDrive using GoogleAPI, GoogleAppScript[GAS]	-		-	
					Watch videos on smartphone Posting images to LINE with ESP32 this time

1-2. Camera use with ESP32 (price details)


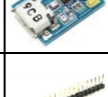


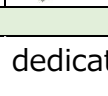
*Please note that the cost varies depending on the season.
* Excel can be downloaded from the Hobby-IT site.

①ESP32(WROOM) and OV2640 【¥3930】

NO	Item	quantity	Image	Item	URL(Japanese Shop)	Price(yen)	Note
1	ESP32 development board	1		ESP32-DevKitC-32E ESP32-WROOM-32E development board 4MB	https://akizukidenshi.com/catalog/g/gM-15673/	1600	19Pin x 2 rows
2	Breadboard 6 hole [EIC-3901]	1		Breadboard 6 hole plate EIC-3901	https://akizukidenshi.com/catalog/g/gP-12366/	460	
3	Green LED	1		3mm yellow-green LED 570nm 70 degrees OSG8HA3Z74A	https://akizukidenshi.com/catalog/g/gL-11637/	10	For status display
4	OV2640 camera module	1		2 megapixel camera using OV2640 B0011	https://akizukidenshi.com/catalog/g/gM-13197/	1680	
5	jumper cable	1		Cable with connector 20cm 40P male/female	https://akizukidenshi.com/catalog/g/gC-17228/	180	This time I used a handheld, so I haven't checked the connector shape etc.
total						3,930	Separate shipping fee is required






I omitted the jumper wire set and the LED resistor for wiring.

②M5Stack UnitCam 【¥4046】

NO	Item	quantity	Image	Item	Shop-URL	Price	Note
1	UnitCam	1		Unit Cam Wi-Fi Camera DIY Kit (OV2640)	https://shop.m5stack.com/collec-tions/m5-cameras https://www.marutsu.co.jp/pc/i/2228284/	M5Stack \$18.95 marutsu 2946	
2	USB serial conversion module	1		FT234X ultra-compact USB serial conversion module	https://akizukidenshi.com/catalog/g/gM-08461/	680	Even if you use many UnitCams, you only need one
3	Thin pin header 1 x 20	1		Thin pin header 1 x 20	https://akizukidenshi.com/catalog/g/gC-04398/	20	
4	jumper cable	1		Cable with connector 20cm 40P male/female	https://akizukidenshi.com/catalog/g/gC-17228/	180	This time I used a handheld, so I haven't checked
5	bread board	1		bread board BB-801	https://akizukidenshi.com/catalog/g/gP-05294/	220	
total						4,046	Separate shipping fee is required



There is also a dedicated Uploader, but this item is selected this time because it is versatile

③ESP32(WROVER) and OV2640 【¥4080】

NO	Item	quantity	Image	Item	URL(Japanese Shop)	Price(yen)	Note
1	ESP32 development board	1		ESP32-DevKitC-32E ESP32-WROVER-32E development board 8MB	https://akizukidenshi.com/catalog/g/gM-15674/	1750	19Pin x 2 rows
2	Breadboard 6 hole [EIC-3901]	1		Breadboard 6 hole plate EIC-3901	https://akizukidenshi.com/catalog/g/gP-12366/	460	
3	Green LED	1		3mm yellow-green LED 570nm 70 degrees OSG8HA3Z74A	https://akizukidenshi.com/catalog/g/gL-11637/	10	For status display
4	OV2640 camera module	1		2 megapixel camera using OV2640 B0011	https://akizukidenshi.com/catalog/g/gM-13197/	1680	
5	jumper cable	1		Cable with connector 20cm 40P male/female	https://akizukidenshi.com/catalog/g/gC-17228/	180	This time I used a handheld, so I haven't checked the connector shape etc.
total						4,080	Separate shipping fee is required

I omitted the jumper wire set and the LED resistor for wiring.

④M5Stack TimerCamera(OV3660) 【¥2596/2860】

NO	Item	quantity	Image	Item	Shop-URL	Price	Note
1	Timer Camera X	1		ESP32 PSRAM Timer Camera X (OV3660)	https://shop.m5stack.com/collec-tions/m5-cameras https://www.switch-science.com/products/6742	M5Stack \$17.95 SWITCH SIENCE 2596	viewing angle 66.5°
1	Timer Camera F	1		ESP32 PSRAM Timer Camera F (OV3660)	https://shop.m5stack.com/collec-tions/m5-cameras https://www.switch-science.com/products/6786	M5Stack \$18.95 SWITCH SIENCE 2860	viewing angle 120°
Total						2,860	Separate shipping fee is required

X/F is the difference in viewing angle.

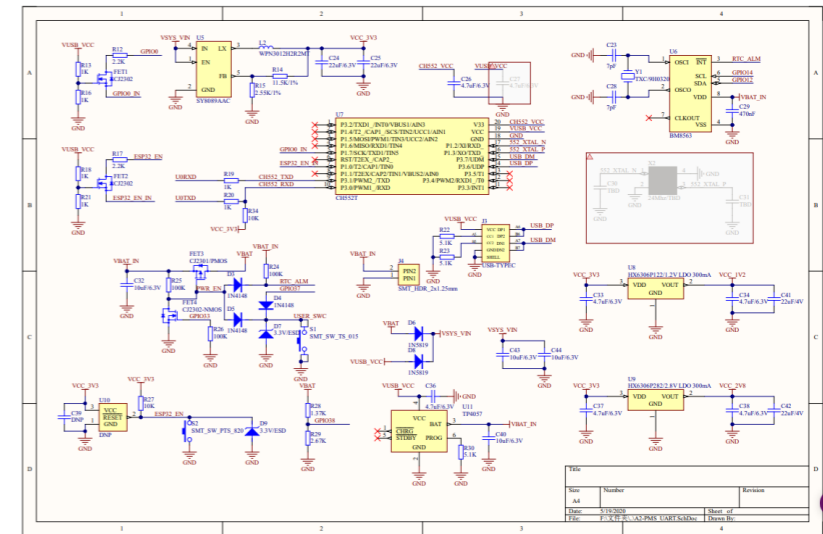
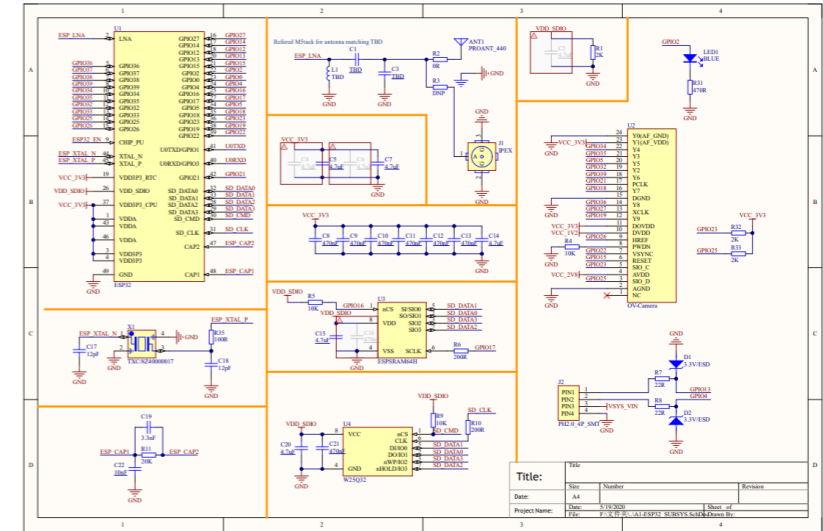
Development is possible with a personal computer with a micro USB cable.

1-3. TimerCamera

● Pin Map

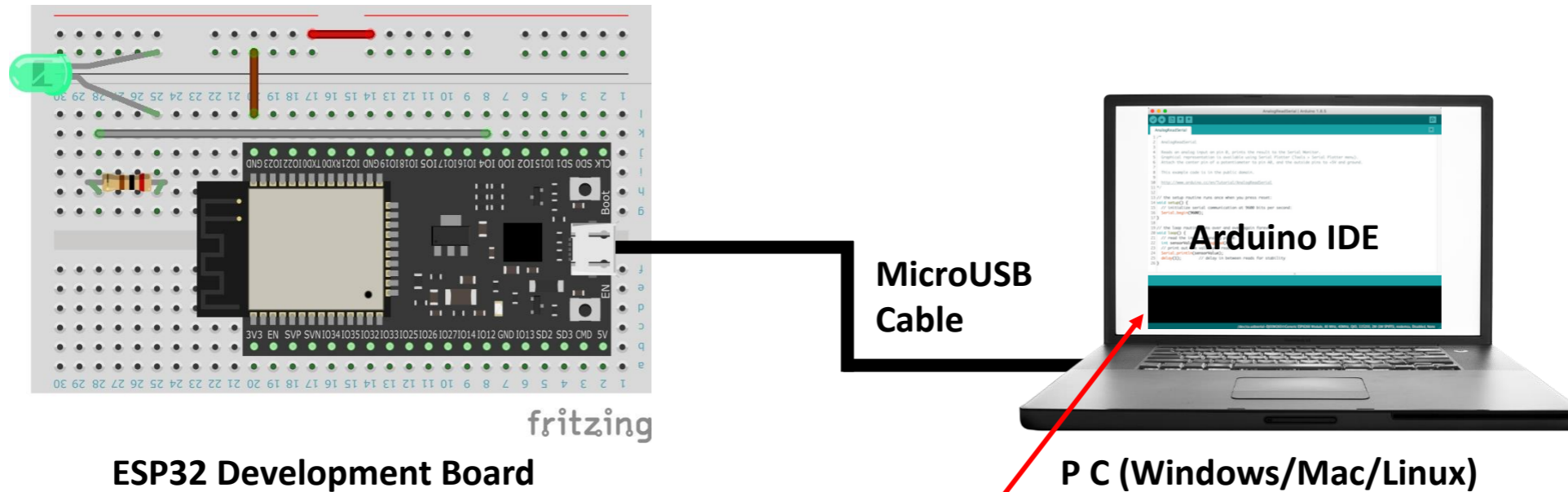
Interface	Camera Pin	TimerCamera
SCCB Clock	SIOC	IO23
SCCB Data	SIOD	IO25
System Clock	XCLK	IO27
Vertical Sync	VSYNC	IO22
Horizontal Reference	HREF	IO26
Pixel Clock	PCLK	IO21
Pixel Data Bit 0	D0	IO32
Pixel Data Bit 1	D1	IO35
Pixel Data Bit 2	D2	IO34
Pixel Data Bit 3	D3	IO5
Pixel Data Bit 4	D4	IO39
Pixel Data Bit 5	D5	IO18
Pixel Data Bit 6	D6	IO36
Pixel Data Bit 7	D7	IO19
Camera Reset	RESET	IO15
Camera Power Down	PWDN	-1
Power Supply 3.3V	3V3	3V3
Ground	GND	GND

● Schematic



2. the development environment “Arduino”

We will use Arduino as the development environment.



【Arduino Official site】

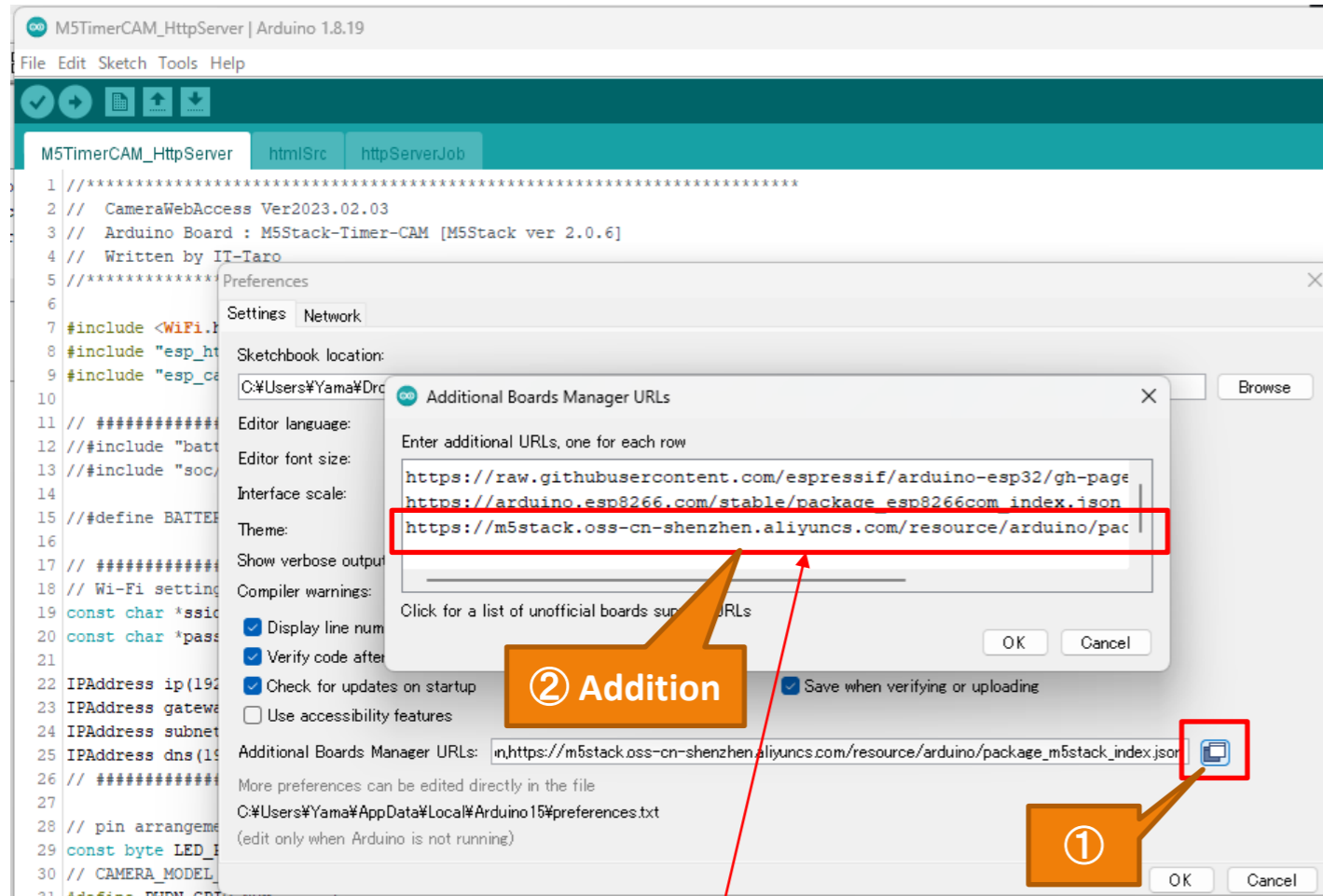
<https://www.arduino.cc/>

Downloadable

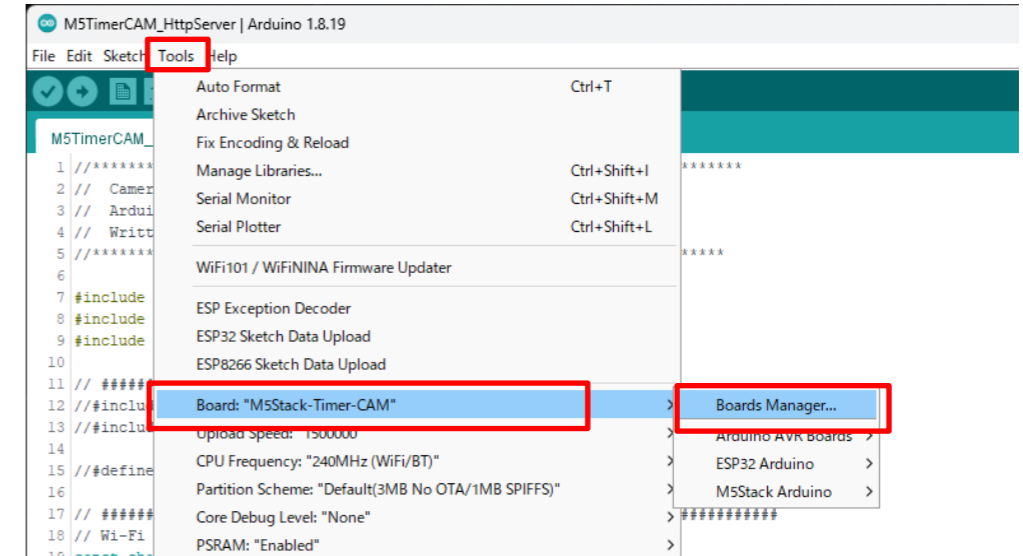
3-1. Arduino settings (Board settings)

M5Stack Official ArduinoIDE Setting
https://docs.m5stack.com/en/quick_start/timer_cam/arduino

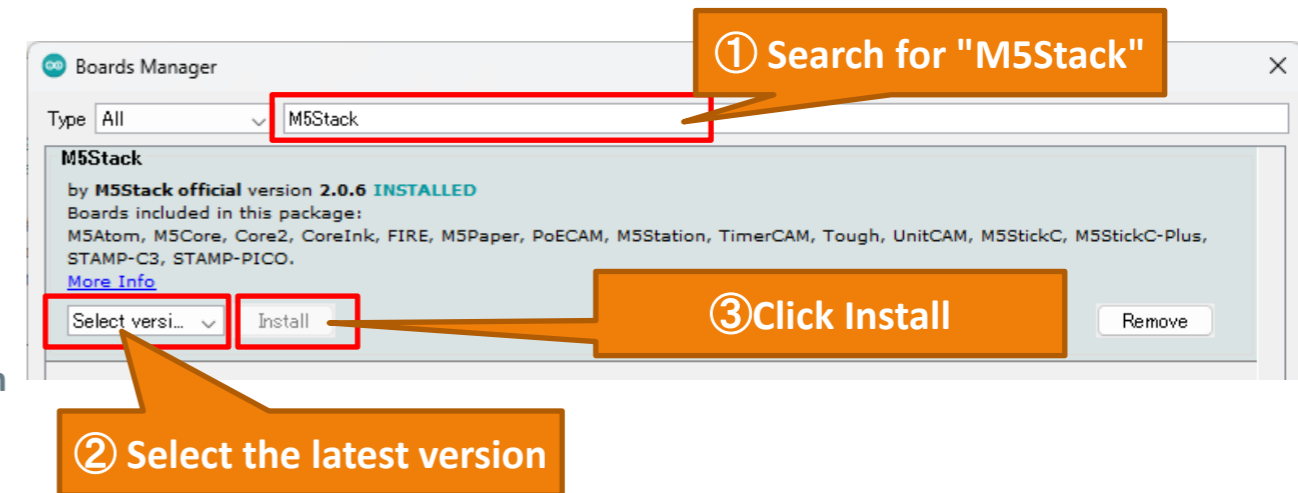
1) Add Additional Board Manager setting from ArduinoIDE setting



2) Launch Board Manager



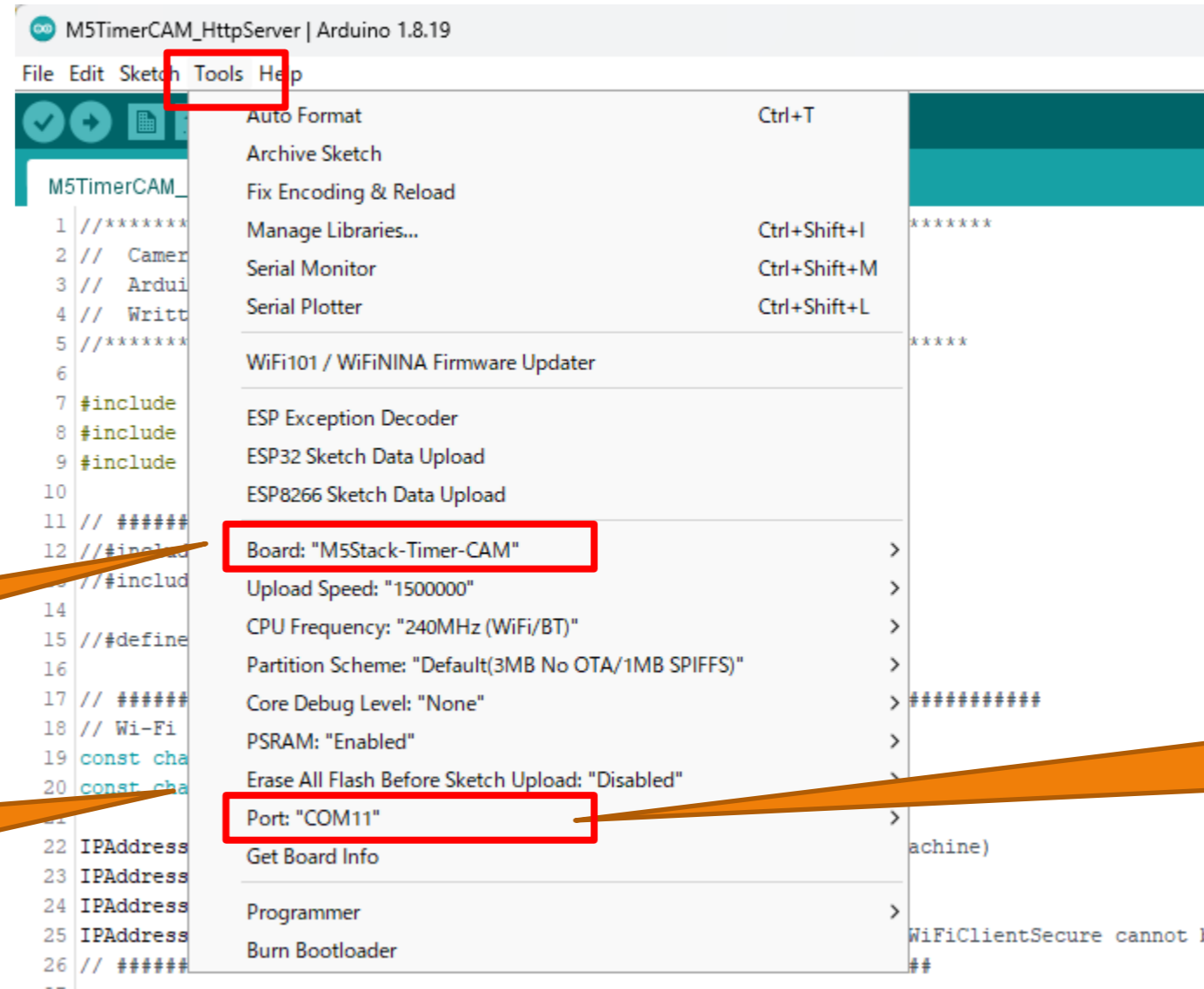
3) Install M5Stack



set value :
https://m5stack.oss-cn-shenzhen.aliyuncs.com/resource/arduino/package_m5stack_index.json

3-1. Arduino settings (Board settings)

4) Set Board to "M5Stack-Timer-CAM"



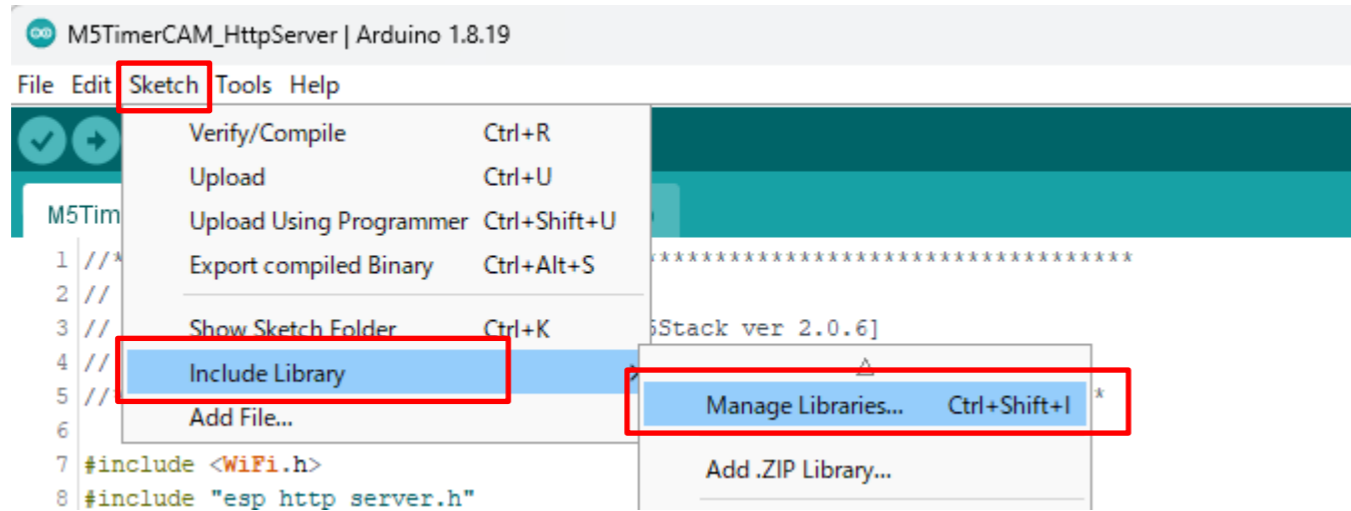
Select "M5Stack-Timer-CAM"

No other settings changed (with default value)

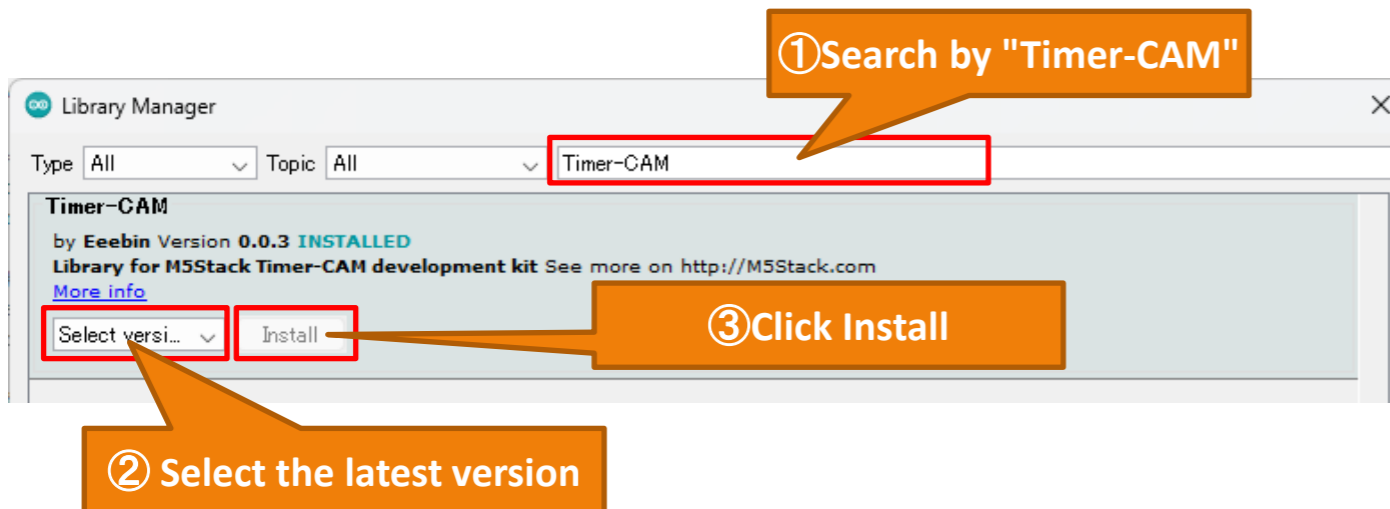
For Port, select the port to which TimerCamera is connected [Write error when selection fails]

3-2. Arduino settings (Add Library)

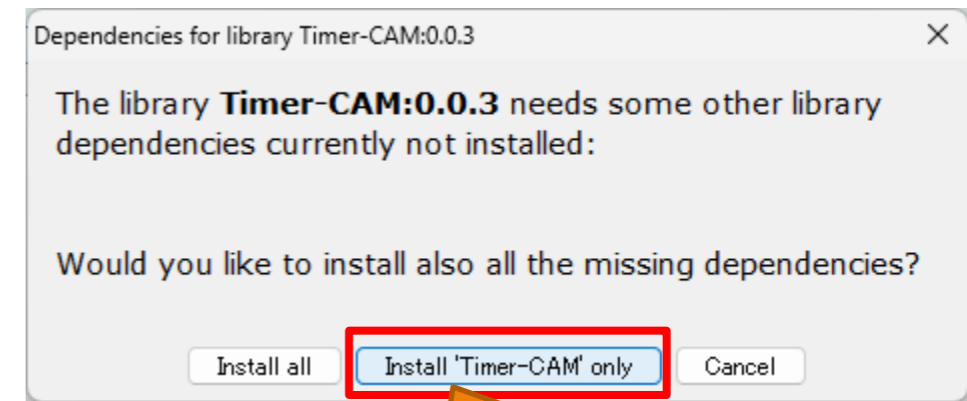
1) Start Library Manager



2) Install "Timer-CAM"



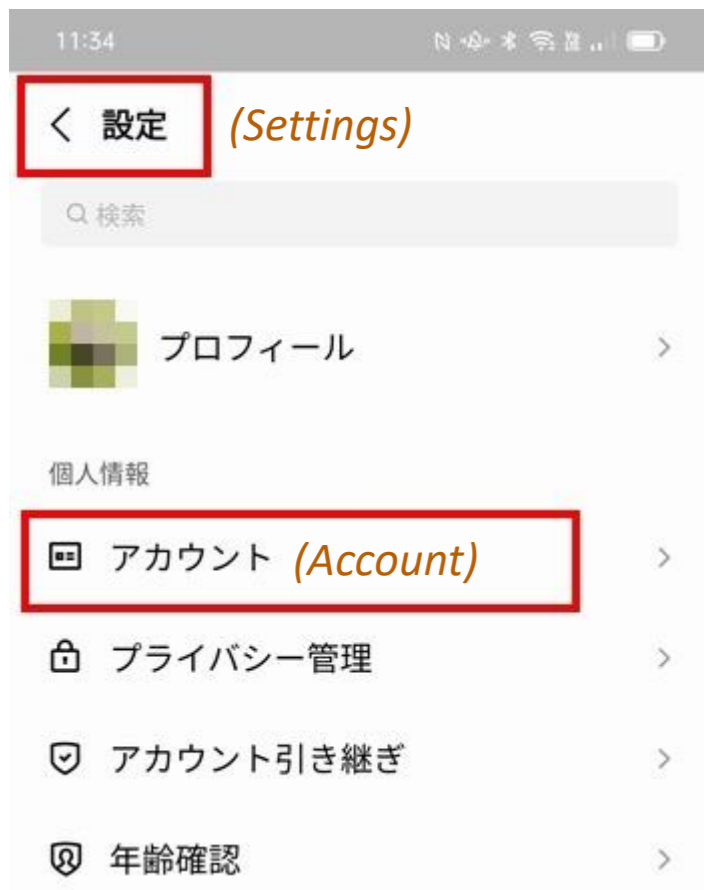
3) Install only "Timer-CAM"



just install this
(When operation is NG, install all)

4-1. LINE settings (token acquisition)

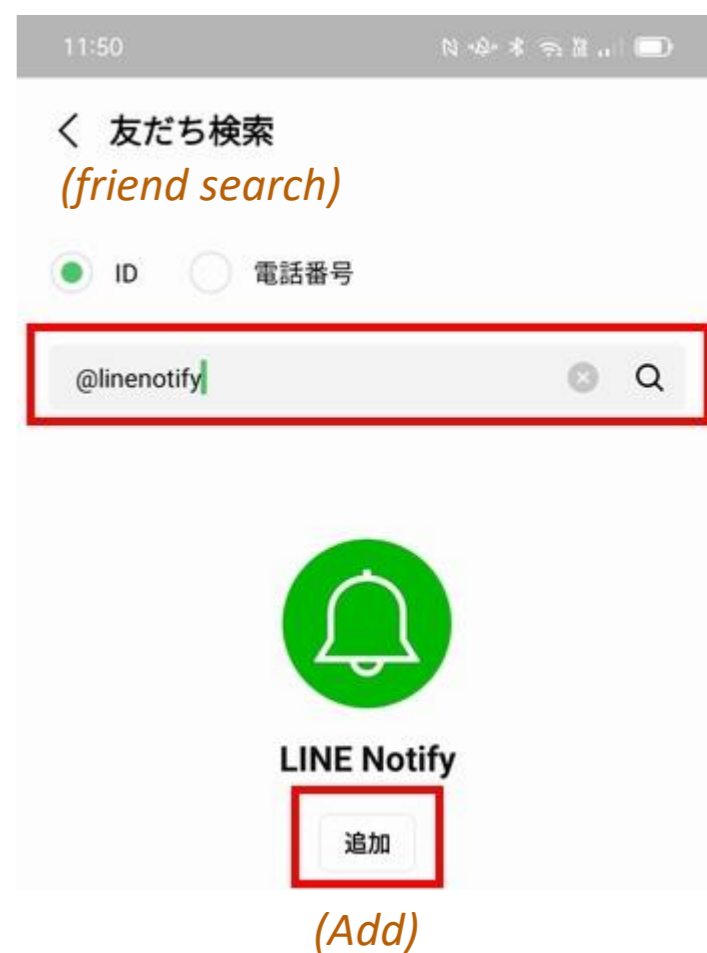
1) Select an account from "Settings" on the smartphone LINE app



2) Turn on "Allow login"

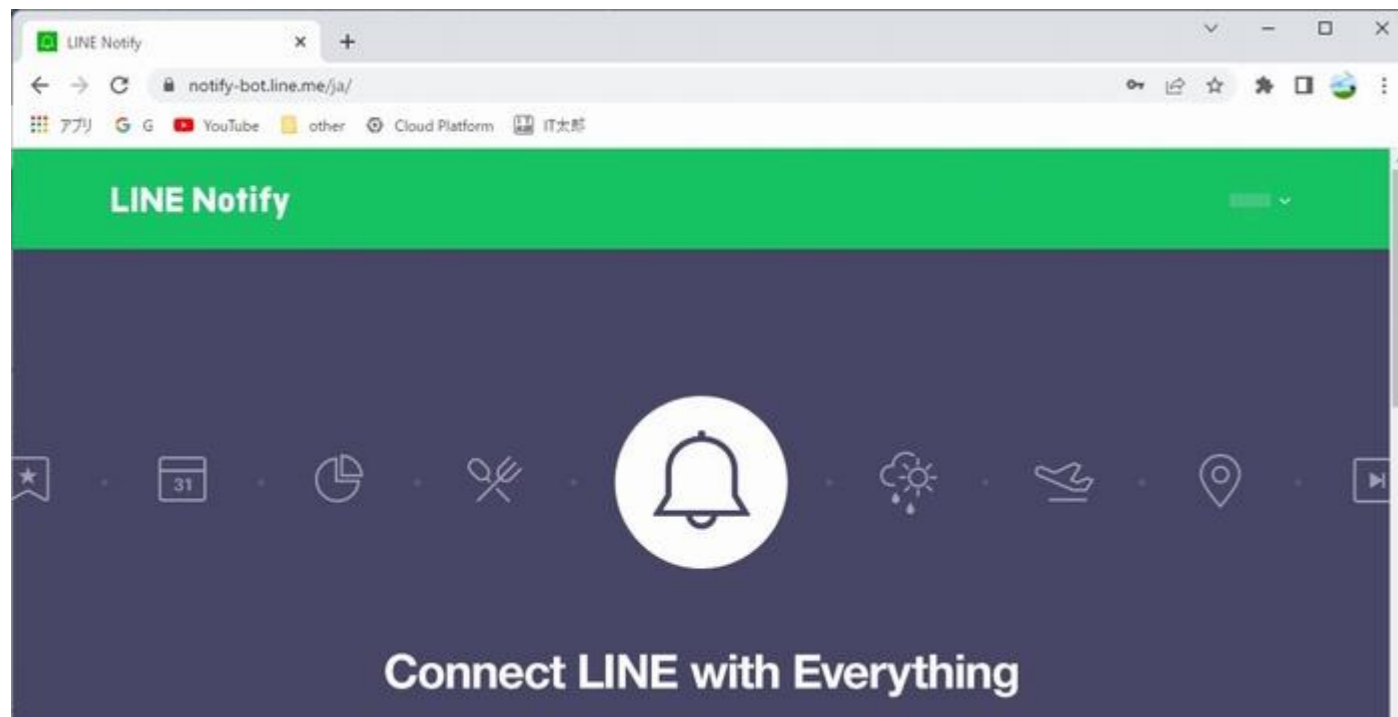


3) Add friends by searching for "@linenotify"



4-2. LINE settings (token acquisition)

4) Access LINE Notify on your computer and log in with your LINE account.



<https://notify-bot.line.me/ja/>

5) Select "My Page" from the menu on the upper right

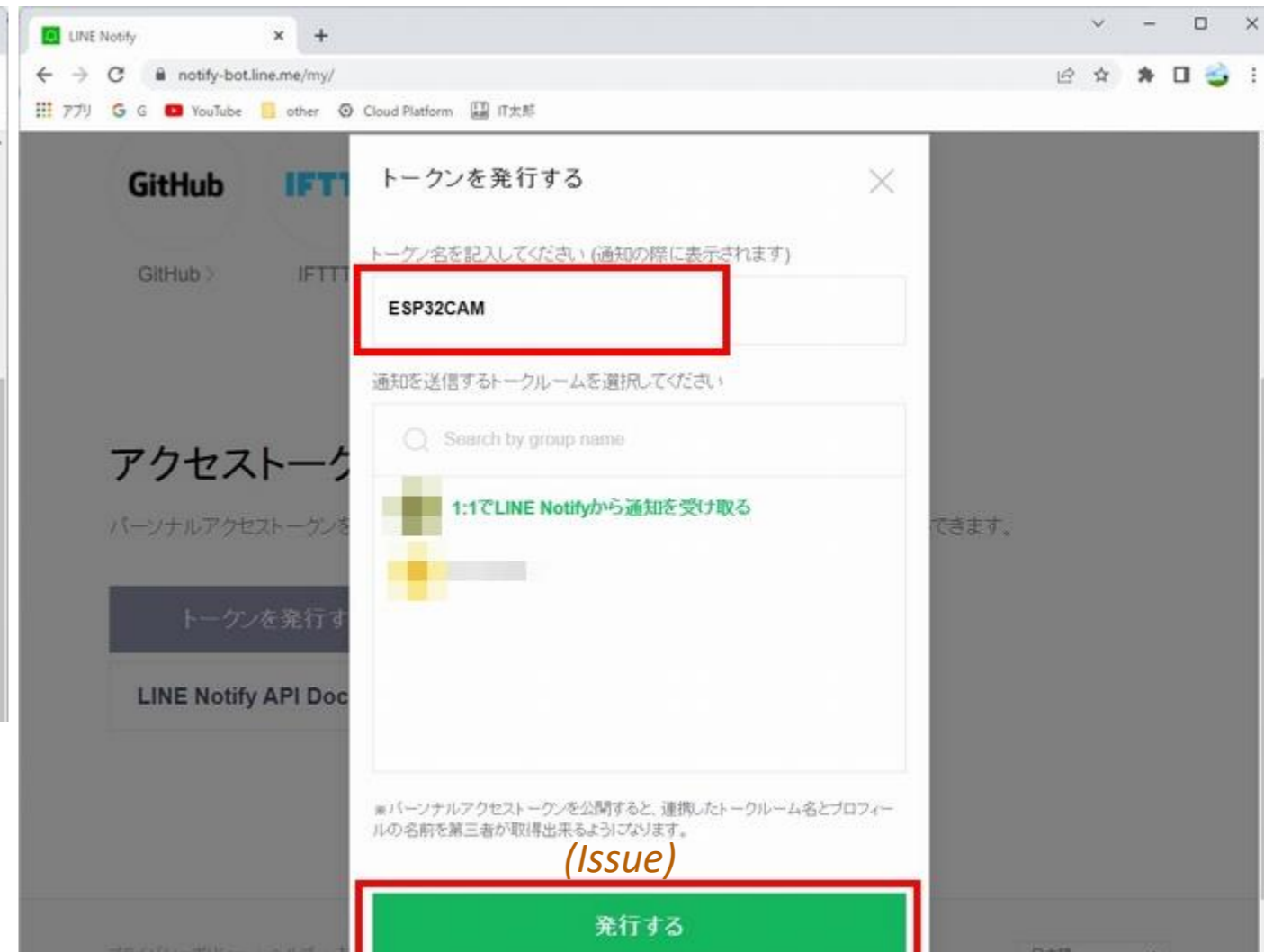


4-3. LINE settings (token acquisition)

6) Issue a token.

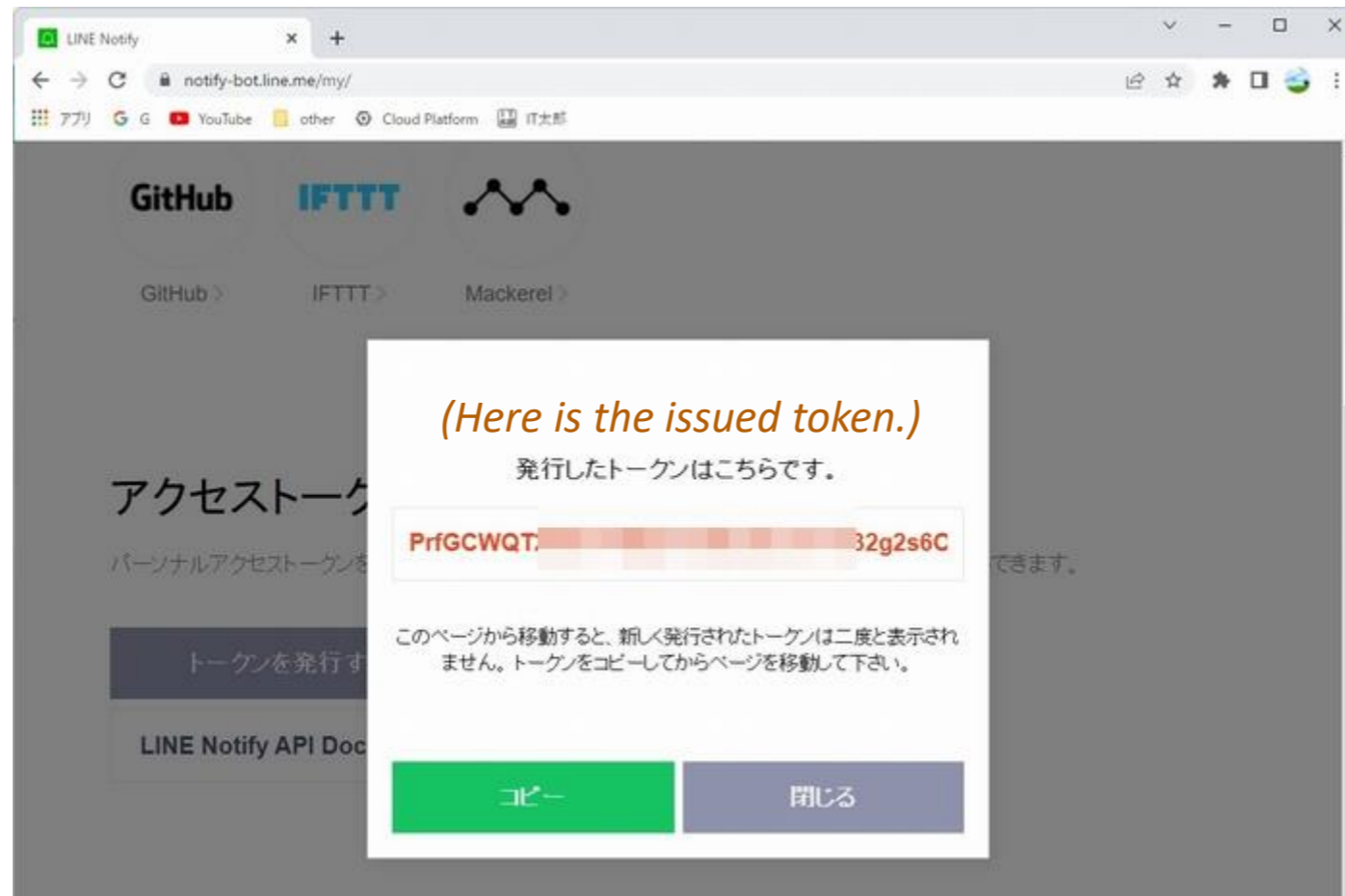


7) Enter the token name and issue.



4-4. LINE settings (token acquisition)

8) Get the issued token. (Recorded for inclusion in the program.)



5. Arduino program (global definition)

```
7 #include <WiFi.h>
8 #include <WiFiClientSecure.h>
9 #include "esp_camera.h"
10
11 // ##### for Battery Use #####
12 //#include "battery.h"
13 //#include "soc/rtc_cntl_reg.h" // for BrouwnoutDetector Disable
14
15 //#define BATTERY_ENABLE
16
17 // ##### Line, Wi-Fi settings (Preferences) #####
18 String lineToken      = "#### TOKEN ####"; // [★change required]
19
20 const char *ssid      = "#### SSID ####"; // [★change required]
21 const char *password  = "### PASSWORD ###"; // [★change required]
22 // #####
23 const char* lineServer = "notify-api.line.me";
24
25 // LED Pin Setting
26 const byte LED_PIN    = 2; // Green LED
27
28 // CAMERA_MODEL_M5_UNIT_CAM
29 #define PWDN_GPIO_NUM  -1
30 #define RESET_GPIO_NUM 15
31 #define XCLK_GPIO_NUM  27
32 #define SIOD_GPIO_NUM  25
33 #define SIOC_GPIO_NUM  23
34
35 #define Y9_GPIO_NUM    19
36 #define Y8_GPIO_NUM    36
37 #define Y7_GPIO_NUM    18
38 #define Y6_GPIO_NUM    39
39 #define Y5_GPIO_NUM     5
40 #define Y4_GPIO_NUM    34
41 #define Y3_GPIO_NUM    35
42 #define Y2_GPIO_NUM    32
43 #define VSYNC_GPIO_NUM 22
44 #define HREF_GPIO_NUM  26
45 #define PCLK_GPIO_NUM  21
46
47 // Global Values
48 WiFiClientSecure httpsClient;
49 bool ledFlag      = true; // LED Control Flag
50 camera_fb_t * fb;
```

loading the library

LINE-Token, Wi-Fi settings

Need to change settings

LED port settings

Camera port settings

HTTPS client, LED state flags, camera buffer variable definitions

5. Arduino program (Setup function)

```
52 // Setup Function
53 void setup() {
54     Serial.begin(115200);
55
56 // For Battery Use
57 #ifndef BATTERY_ENABLE
58     WRITE_PERI_REG(RTC_CNTL_BROWN_OUT_REG, 0); //disable detector
59     bat_init();
60     bat_hold_output();
61 #endif
62 //Serial.setDebugOutput(true);
63 //Serial.println();
64
65 // Camera Setting
66 camera_config_t config;
67 config.ledc_channel = LEDC_CHANNEL_0;
68 config.ledc_timer = LEDC_TIMER_0;
69 config.pin_d0 = Y2_GPIO_NUM;
70 config.pin_d1 = Y3_GPIO_NUM;
71 config.pin_d2 = Y4_GPIO_NUM;
72 config.pin_d3 = Y5_GPIO_NUM;
73 config.pin_d4 = Y6_GPIO_NUM;
74 config.pin_d5 = Y7_GPIO_NUM;
75 config.pin_d6 = Y8_GPIO_NUM;
76 config.pin_d7 = Y9_GPIO_NUM;
77 config.pin_xclk = XCLK_GPIO_NUM;
78 config.pin_pclk = PCLK_GPIO_NUM;
79 config.pin_vsync = VSYNC_GPIO_NUM;
80 config.pin_href = HREF_GPIO_NUM;
81 config.pin_sscb_sda = SIOD_GPIO_NUM;
82 config.pin_sscb_scl = SIOC_GPIO_NUM;
83 config.pin_pwdn = PWDN_GPIO_NUM;
84 config.pin_reset = RESET_GPIO_NUM;
85 config.xclk_freq_hz = 20000000;
86 config.pixel_format = PIXFORMAT_JPEG;
87 // Image size setting: QVGA(320x240), CIF(400x296), HVGA(480x320), VGA(640x480), SVGA(800x600), XGA(1024x768)
88 config.frame_size = FRAMESIZE_XGA;
89 config.jpeg_quality = 10;
90 config.fb_count = 2;
91
92 // camera init
93 esp_err_t err = esp_camera_init(&config);
94 if (err != ESP_OK) {
95     Serial.printf("Camera init failed with error 0x%x", err);
96     return;
97 }
```

Start serial monitor

Turn off BrownOUT check when using battery
[Enable setting if an error occurs immediately and restarts]

Camera port settings and initialization

Image size setting
XGA(1024*768)

5. Arduino program (Setup function)

```
98 /*sensor_t *s = esp_camera_sensor_get();
99 // initial sensors are flipped vertically and colors are a bit saturated
100 s->set_vflip(s, 1); // flip it back
101 s->set_brightness(s, 1); // up the blightness just a bit
102 s->set_saturation(s, -2); // lower the saturation*/
103
104 // ##### PIN setting start #####
105 pinMode ( LED_PIN, OUTPUT );
106
107 // ##### Wireless Wi-Fi connection #####
108 WiFi.begin ( ssid, password );
109 while ( WiFi.status() != WL_CONNECTED ) { // infinite loop until connected
110     // LED flashes every second while connected
111     ledFlag = !ledFlag;
112     digitalWrite(LED_PIN, ledFlag);
113     delay ( 1000 );
114     Serial.print ( "." );
115 }
116 // Wi-Fi connection completed (IP address display)
117 Serial.print ( "Wi-Fi Connected! IP address: " );
118 Serial.println ( WiFi.localIP() );
119 Serial.println ( );
120 // LED lights when Wi-Fi is connected (Wi-Fi connection status)
121 digitalWrite(LED_PIN, true);
122
123 // ##### HTTPS certificate check setting #####
124 // Skip Server certificate check (required since 1.0.5)
125 httpsClient.setInsecure();//skip verification
126 //httpsClient.setCACert(rootCA);// It is also possible to obtain a root certificate in advance using a web browser and
127
128 // ##### Get Image #####
129 Serial.println("Start get JPG");
130 getCameraJPG();
131 // ##### Post to LINE CLOUD #####
132 Serial.println("Start Post Line");
133 postLine();
134
135 Serial.println("Line Completed!!!");
136 }
```

LED port settings

Wi-Fi connection processing

Certificate check skip processing
(Encryption is enforced, but server correctness check for URL is skipped)

Acquisition processing of JPEG image by camera

Image posting process to LINE

[reference]

Regarding the usage when the certificate is checked, it is implemented in the following post "Smart Remote Controller (smartphone from outdoors, AI speaker cooperation) "
<https://hobby-it.com/smartremo7/>

5. Arduino program (postLine function)

```
148 // Post image to LINE
149 void postLine() {
150
151     // Connect to LINE Cloud
152     Serial.println("Connect to " + String(lineServer));
153     if (httpClient.connect(lineServer, 443)) {
154         Serial.println("Connection successful");
155
156         String messageData = "--foo_bar_baz\r\n"
157             "Content-Disposition: form-data; name=\"message\"\r\n\r\n"
158             "ESP32CAM Post\r\n"; // message to display
159         String startBoundary = "--foo_bar_baz\r\n"
160             "Content-Disposition: form-data; name=\"imageFile\"; filename=\"esp32cam.jpg\"\r\nContent-Type: image/jpeg\r\n\r\n";
161         String endBoundary = "\r\n--foo_bar_baz--";
162
163         unsigned long contentsLength = messageData.length() + startBoundary.length() + fb->len + endBoundary.length();
164         String header = "POST /api/notify HTTP/1.0\r\n"
165             "HOST: " + String(lineServer) + "\r\n" +
166             "Connection: close\r\n" +
167             "content-type: multipart/form-data;boundary=foo_bar_baz\r\n" +
168             "content-length: " + String(contentsLength) + "\r\n" +
169             "authorization: Bearer " + lineToken + "\r\n\r\n";
170
171         Serial.println("Send JPEG DATA by API");
172         httpClient.print(header);
173         httpClient.print(messageData);
174         httpClient.print(startBoundary);
175         // JPEG data is separated into 1000 bytes and POSTed
176         unsigned long dataLength = fb->len;
177         uint8_t* bufAddr = fb->buf;
178         for(unsigned long i = 0; i < dataLength ;i=i+1000) {
179             if ( (i + 1000) < dataLength ) {
180                 httpClient.write(( bufAddr + i ), 1000);
181             } else if (dataLength%1000 != 0) {
182                 httpClient.write(( bufAddr + i ), dataLength%1000);
183             }
184         }
185         httpClient.print(endBoundary);
186
187         Serial.println("Waiting for response.");
188         while (httpClient.connected()) {
189             String line = httpClient.readStringUntil('\n');
190             if (line == "\r") {
191                 Serial.println("headers received");
192                 break;
193             }
194         }
195     }
196 }
```

Connection processing to the server
(inside the IF statement if the connection is successful)

Header creation process

Header sending process

Camera image transmission processing
(Sent in units of 1000 bytes)

Boundary transmission of end of image transmission

Waiting for response from server (waiting for newline code)

5. Arduino program (postLine/getCameraJPEG function)

```
194     }  
195     while (httpsClient.available()) {  
196         char c = httpsClient.read();  
197         Serial.write(c);  
198     }  
199 } else {  
200     Serial.println("Connected to " + String(lineServer) + " failed.");  
201 }  
202 httpsClient.stop();  
203 Serial.println();  
204 Serial.println("Finish httpsClient");  
205 }  
206  
207 // Get JPEG image with OV3660  
208 void getCameraJPEG(){  
209     fb = esp_camera_fb_get(); // Get JPEG image  
210     if (!fb) {  
211         Serial.printf("Camera capture failed");  
212     }  
213     Serial.printf("JPG: %uB ", (uint32_t)(fb->len));  
214     Serial.println();  
215     // Shooting end processing  
216     esp_camera_fb_return(fb);  
217 }
```

Display the contents received from the server on the serial monitor

Processing when server connection fails

Server connection termination processing

JPEG image acquisition processing in the camera

5. Arduino program (send data)

Sent via HTTP(S) POST

```
POST /api/notify HTTP/1.0
HOST: notify-api.line.me
Connection: close
content-type: multipart/form-data;boundary=foo_bar_baz
content-length: *****LENGTH*****
authorization: Bearer *****TOKEN*****
```

boundary settings

```
--foo_bar_baz
Content-Disposition: form-data; name="message"

ESP32CAM Post
```

boundary

Posted message

```
--foo_bar_baz
Content-Disposition: form-data; name="imageFile"; filename="esp32cam.jpg"
Content-Type: image/jpeg
```

boundary

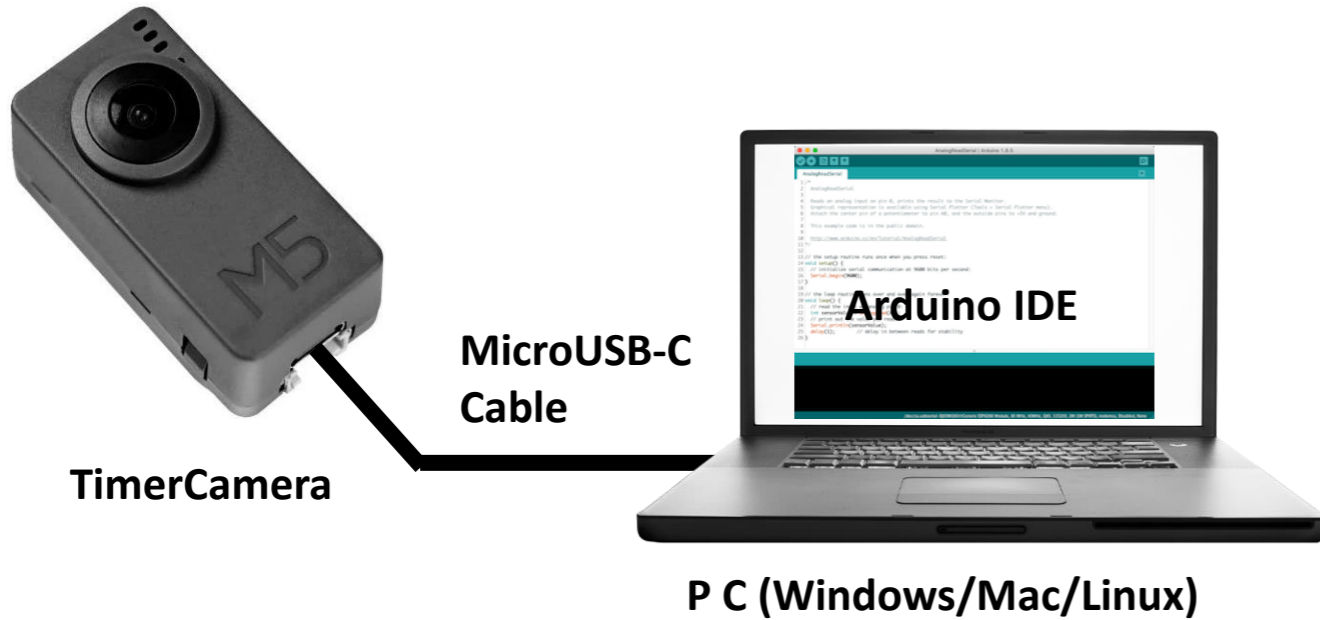
```
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXX JPEG Data XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
--foo_bar_baz--
```

Send 1000 bytes at a time

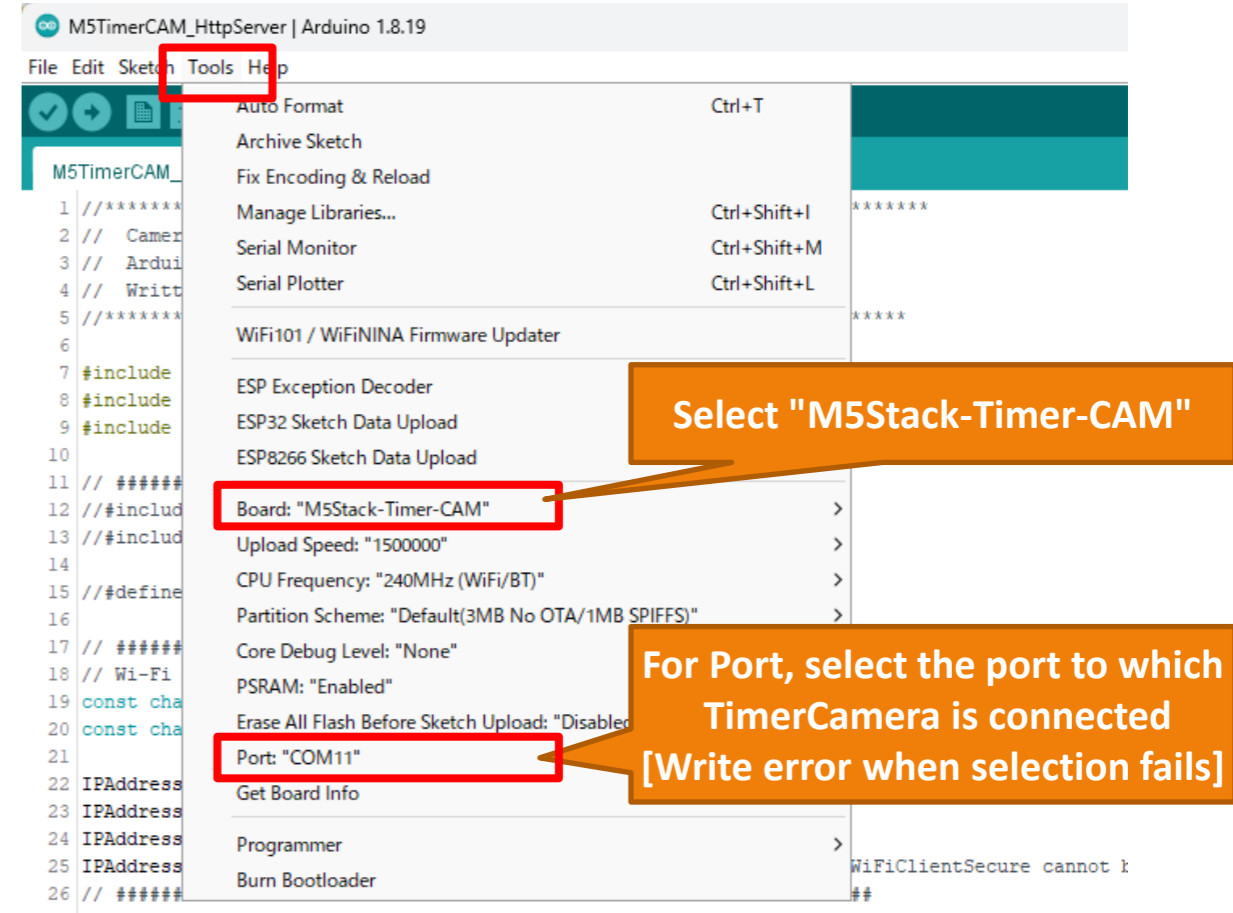
boundary

6-1. Program writing

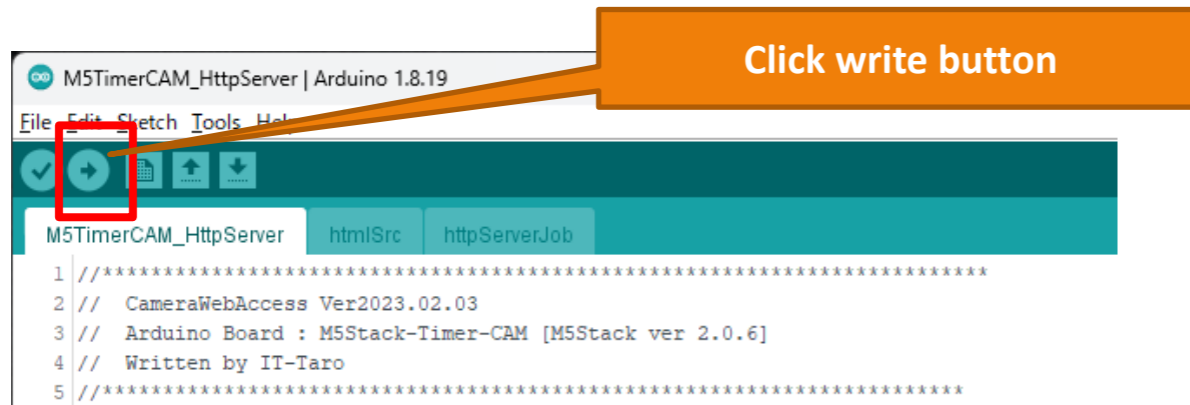
1) Connect TimeCamera with micro USB-C cable



2) Open the program with ArduinoIDE and check the settings again. (Change the Wi-Fi settings [SSID, IP address, etc.] in the program.)

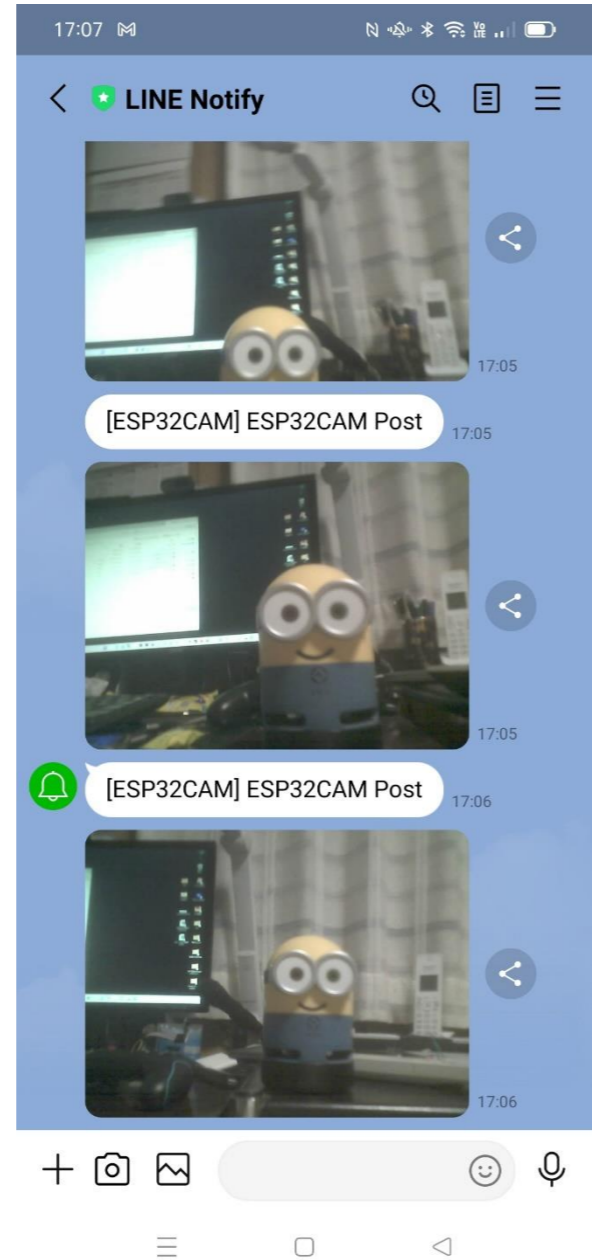


3) Click write button



6-2. Operation check

When TimerCamera starts up, it acquires an image and posts it to LINE.



Posted at the time before the last boot

Posted on last boot

Messages and images posted to
LINE by TimerCamera